



# Documentation

## EVA4201/4301 – User Guide

Evaluation Board for  
80W  
Power Factor Corrected (PFC) Supply

Featured Products: PE4201/PE4301

#### Table of Contents

1.	Revision History .....	2
2.	Safety Instructions.....	3
3.	Introduction .....	3
3.1	Features .....	3
3.2	IC's General Description.....	3
4	How to design an application .....	4
4.1	Given board specification.....	4
4.2	Calculating the Current .....	4
4.3	Inductor .....	6
4.4	Current Sense Resistor.....	7
4.5	Error Amplifier Compensations .....	10
4.6	Self Biasing .....	11
4.7	EMI and Driver SlewRate.....	12
4.8	Start-Up Bypass Rectifier .....	12
5	Description .....	13
5.1	Evaluation Board Specifications.....	14
5.2	Wire bridges .....	14
5.3	Schematic .....	15
5.4	Component Placement.....	16
5.5	Board Picture and Layout .....	17
5.6	Bill of Material.....	18
6	Operating .....	19
6.1	Caution.....	19
6.2	Load .....	19
6.3	AC-Input.....	19
6.4	Power-up Sequence.....	19
7.	List of Abbreviations .....	20
8.	Notes.....	21
9.	Contact Addresses .....	22

#### 1. Revision History

Version	Date	Changes	Page
Initial Version V1.0	12/2008		
V1.1	04/2013	Formula (2)	4

## 2. Safety Instructions

**Please take caution - the board operates at 405V DC and is directly plugged into the power network. Operating this Board requires an isolated transformer!**

The EVA4201/4301 was designed to help understand and evaluate the features of two Power Factor Correction IC's. Used external devices are standard components chosen for safe operation and do not represent a completely fine-tuned OEM application. The BOM (bill of material) for a final application may look slightly different.

The board can also be used with PEs high precision PFC ICs, the PE4202 and the PE4302.

## 3. Introduction

### 3.1 Features

The board is designed to support applications of our two PFC-IC's PE4201 and PE4301

#### PE4201

- Low Total Harmonic Distortion (THD)
- Low StartUp Current (<5 $\mu$ A)
- Low Operating Current (<450 $\mu$ A)
- Disable Function (<170 $\mu$ A)
- Under-Voltage Lockout with >8V Hysteresis
- Over voltage and Over current protection with separate Reference
- Reduced operating Frequency at low Output Power
- High Efficiency at high and low Output Power
- Internal Clamping Resistor at G
- fast Driver turn 'off'
- very fast Driver 'off' at over current sense
- Driver load up to 5nF

#### PE4301

- Wide Range Input
- Low Total Harmonic Distortion (THD)
- Low Operating Current (<550 $\mu$ A)
- Disable Function (<100 $\mu$ A)
- Under-Voltage Lockout with >8V Hysteresis
- Over voltage protection, Peak current protection and Open loop protection with separate Reference
- low Peak current protection threshold
- Operating Frequency between 40 kHz and 250 kHz dependent upon load
- High Efficiency at high and low Output Power
- Internal Clamping Resistor at Driver
- Soft start
- fast Driver Switch 'off'

#### Application with PE4201/PE4301

- Active power factor correction
- Switch mode power supplies

### 3.2 IC's General Description

The **PE4201** and **PE4301** are wide input range controller ICs for active power factor correction converters. Both ICs provide many protection functions, such over voltage protection, open loop protection, supply under voltage lockout, output under voltage protection and peak current limit protection. These protection functions are working with separate reference.

The **PE4201** operates in the CRM with voltage mode PWM control and in DCM under light load condition. The maximum switching frequency is clamped with an internal delay circuit. Compensations for voltage loop are external.

The **PE4301** IC operates in the CCM with average current control. The switching frequency depends upon load. At high output load the frequency is low and with low load the frequency is high. The Compensation for voltage loop and soft start is external.

For more information refer to the datasheets.

## 4 How to design an application

### 4.1 Given board specification

#### PE4201/PE4301

The board setup in the original state has the following specification parameters. The following chapters show, what has to be changed to design an active PFC supply towards different parameters. Please take caution when calculating. Wrong device parameter calculation can damage the Evaluation board or other devices.

AC Line Input voltage	85 VAC ... 265 VAC
AC Line Frequency	47 ... 63Hz
Switching Frequency	40 ... 250 kHz
Output voltage	340 -405V DC (adjustable)
Output Load	max 80W
Over Voltage Threshold	416V DC

### 4.2 Calculating the Current

#### PE4201

The input power:

$$P_{in} = \frac{P_{out}}{\eta} = \frac{80W}{92\%} = 86,96W \quad (1)$$

The input current:

$$I_{ACin\_LL} = \frac{P_{in} * D}{V_{AC}} = \frac{86,96W * 0,66}{110V} = 0,52A \quad (2)$$

$$I_{ACin\_HL} = \frac{P_{in}}{V_{AC}} = \frac{86,96W}{265V} = 0,33A \quad (3)$$

D... Duty Cycle at 110V

The peak current:  $I_{pk\_LL} = 2 * \sqrt{2} * I_{ACin\_LL} = 2 * \sqrt{2} * 0,52A = 1,48A \quad (4)$

$$I_{pk\_HL} = 2 * \sqrt{2} * I_{ACin\_HL} = 2 * \sqrt{2} * 0,33A = 0,93A \quad (5)$$

This peak current affects the component selection on the current sense resistor, Power-MOSFET, diode and inductor.

**PE4301**

The input power:

$$P_{in} = \frac{P_{out}}{\eta} = \frac{80W}{92\%} = 86,96W \quad (6)$$

The input current:

$$I_{ACin\_LL} = \frac{P_{in}}{V_{AC}} = \frac{86,96W}{110V} = 0,40A \quad (7)$$

$$I_{ACin\_HL} = \frac{P_{in}}{V_{AC}} = \frac{86,96W}{265V} = 0,33A \quad (8)$$

The ripple current  $\Delta I$  is set to 20%

$$\Delta I_{LL} = 0,2 * \sqrt{2} * I_{ACin\_LL} = 0,2 * \sqrt{2} * 0,40A = 0,11A \quad (9)$$

$$\Delta I_{HL} = 0,2 * \sqrt{2} * I_{ACin\_HL} = 0,2 * \sqrt{2} * 0,33A = 0,093A \quad (10)$$

The peak current:

$$I_{pk\_LL} = \sqrt{2} * I_{ACin\_LL} + \frac{\Delta I_{LL}}{2} = \sqrt{2} * 0,40A + \frac{0,22}{2} = 0,61A \quad (11)$$

$$I_{pk\_HL} = \sqrt{2} * I_{ACin\_HL} + \frac{\Delta I_{LL}}{2} = \sqrt{2} * 0,33A + \frac{0,22}{2} = 0,51A \quad (12)$$

This peak current affects the component selection on the current sense resistor, MOSFET, diode and inductor.

#### 4.3 Inductor

##### PE4201

For CRM operation, the maximum 'on' time and the maximum 'off' time control the lowest frequency. The minimum CRM inductance  $L_{(CRM)}$  at low and high line input voltage can be calculated as follows:

$$L_{(CRM)} = \frac{V_{out} - V_{in}}{V_{out}} * \frac{V_{in}}{I_{pk}} * \frac{1}{f} \quad (13)$$

$$L_{(CRM)} = \frac{405V - \sqrt{2} * 110V}{405V} * \frac{\sqrt{2} * 110V}{1,48A} * \frac{1}{40kHz} = 1623\mu H \quad (14)$$

$$L_{(CRM)} = \frac{405V - \sqrt{2} * 265V}{405V} * \frac{\sqrt{2} * 265V}{0,93A} * \frac{1}{40kHz} = 754\mu H \quad (15)$$

For high line voltage and high output power the inductor has to have a nominal inductance of 400 $\mu$ H. The switching frequency at low line voltage can be calculated according to equation (16):

$$f = \frac{V_{out} - V_{in}}{V_{out}} * \frac{V_{in}}{I_{pk}} * \frac{1}{L_{(CRM)}} \quad (16)$$

$$f = \frac{405V - \sqrt{2} * 110V}{405V} * \frac{\sqrt{2} * 110V}{1,48A} * \frac{1}{1623\mu H} = 39,9kHz \quad (17)$$

##### PE4301

For CCM operation, the maximum 'on' time and the maximum 'off' time control are the lowest frequencies. The minimum CCM inductance  $L_{(CCM)}$  at low and high line input voltage can be calculated as follows:

Duty Cycle

$$D = \frac{V_{out} - V_{in}}{V_{out}} \quad (18)$$

$$D_{LL} = \frac{405V - \sqrt{2} * 110V}{405} V = 0,615 \quad (19)$$

$$D_{HL} = \frac{405V - \sqrt{2} * 265V}{405} V = 0,074 \quad (20)$$

CCM Inductor

$$L_{CCM} = \frac{\sqrt{2} * V_{in} * D}{f * \Delta I} \quad (21)$$

$$L_{CCM\_LL} = \frac{\sqrt{2} * 110V * 0,615}{40kHz * 0,11A} = 21425 \mu H \quad (22)$$

$$L_{CCM\_HL} = \frac{\sqrt{2} * 265V * 0,074}{40kHz * 0,093A} = 7536 \mu H \quad (23)$$

For high line voltage and high output power the inductor set to 8000μH.  
The switching frequency at low line voltage obtains as:

$$f = \frac{\sqrt{2} * V_{in} * D}{L_{CCM} * \Delta I} \quad (24)$$

$$f = \frac{\sqrt{2} * 110V * 0,62}{8000\mu H * 0,11A} = 109,6kHz \quad (25)$$

#### 4.4 Current Sense Resistor

##### PE4201

The current sense resistor provides the threshold voltage for the over-current protection function. The maximum inductor peak current is set to 1,48 A.

$$R_s = \frac{V_{SHPCP}}{I_{OCP}} = \frac{0,22V}{1,48A} = 0,15\Omega \quad (26)$$

R<sub>sense</sub>=0,15 Ω

##### PE4301

$$R_s = \frac{V_{CSPCP}}{I_{OCP}} = \frac{0,95V}{0,61A} = 1,55\Omega \quad (27)$$

R<sub>sense</sub>=1,55 Ω

For higher/lower output power the resistor RS has to be reduced/increased and the inductor has to be re-calculated.

## 2.5 Output Bypass Capacitor

### PE4201/PE4301

The bypass capacitor on the output of the circuit has to be able to suppress the ripple of the switching frequency and the residues of the full-wave rectified input frequency ( $2 * f_{in}$ ).

$$C_{out} = \frac{P_{out}}{V_{out}} * \frac{1}{\Delta V_{out}} * \frac{1}{f} \quad (28)$$

It is recommended to use  $4 * f_{in}$  to suppress the sine wave residues of the input voltage for calculation. The ripple shall be assumed to be at 5% of the output voltage.

$$\text{at } 40W : C_{out} = \frac{\sqrt{2} * 40W}{405V} * \frac{1}{0.05 * 405V} * \frac{1}{4 * 50Hz} = 34,2\mu F \quad (29)$$

$$\text{at } 80W : C_{out} = \frac{\sqrt{2} * 80W}{405V} * \frac{1}{0.05 * 405V} * \frac{1}{4 * 50Hz} = 68,7\mu F \quad (30)$$

A capacitor with at least  $47\mu F$  (C13) should be used. It has to withstand the maximum output voltage. The equivalent series resistance (ESR) of the capacitor shall not build up a voltage higher than half the ripple amplitude (2,5% of  $V_{out-max}$ ) at peak-current.

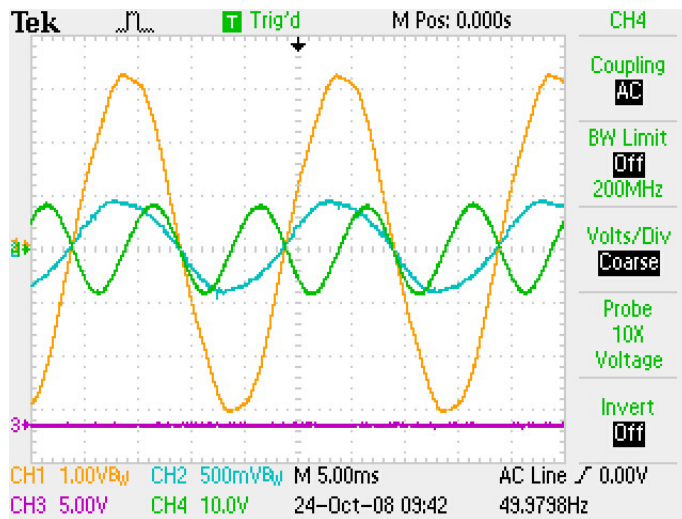
$$R_C = \frac{\Delta V_{out}}{I_{peak}} = \frac{0,025 * 405V}{0,61A} = 16\Omega \quad (31)$$

To reduce the ESR it is recommend to place a capacitor with small ESR in parallel to the high capacitance device. For 2% ripple at minimum switching frequencies the parallel capacitance can be calculated according to equation (23):

$$C_{out2} = \frac{80W}{405V} * \frac{1}{0.02 * 405V} * \frac{1}{40kHz} = 0,61\mu F \quad (32)$$

The capacitor on the board is  $C12=100n/400V$ .





The figure shows the input voltage (230V~) in orange color, the current ( $I_{out}=0.20A$ ) in blue color and the ripple of the output voltage in green color (only AC,  $C_{13}=47\mu$ ,  $C_6=0.1\mu$ ). The ripple is lower than 20V peak-to-peak (<5%).

## Input Filter

### PE4201/PE4301

A high-frequency has to be applied in the primary AC input to reduce reflections from and to the power grid.

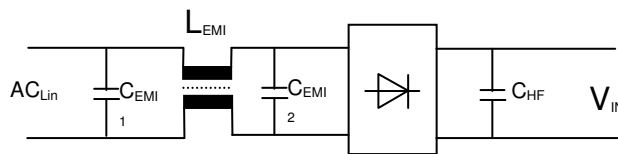


Figure 1: Input Filter

The capacitor  $C_{HF}$  following the bridge rectifier provides the peak current and reduces the voltage ripple. This is typical for a 330nF or for a 470nF capacitor. A high capacitance here will decrease the power factor (C1).

The L-C filter before the bridge rectifier has to suppress the switching frequency by about 20dB. The cut-off frequency shall be below 10kHz.

## 4.5 Error Amplifier Compensations

### PE4201/PE4301

The output of the integrated error amplifier has to be filtered by means of an RC filter for frequency compensation.

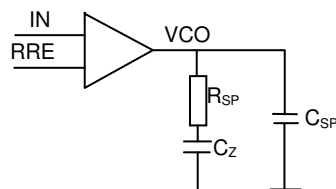


Figure 2: Error Amplifier Compensation

At the same time the capacitor  $C_{SP}$  ensures a soft start function. Capacitance can be calculated according to equation (33). The soft start time is set up at 30ms.

$$C_Z = \frac{t_{ss} * i_{VCOmax}}{V_{RREF}} = \frac{30ms * 20\mu A}{2,53V} = 237nF \quad (33)$$

$C_8=220nF$  shall be chosen here.

The frequency response should have a second pole slightly above twice the power grid frequency. This is set up by  $R_{SP}$  and  $C_Z$ .

$$R_{SP} = \frac{1}{2\pi * f_z * C_z} = \frac{1}{2\pi * 100\text{Hz} * 220\text{nF}} = 6,028\text{k} \quad (34)$$

R4=5,6kOhm shall be chosen here.

The frequency of the second pole shall be at about 1/7 of the switching frequency. This defines the capacitance of C<sub>SP</sub>.

$$C_{SP} = \frac{1}{2\pi * f_z * R_{SP}} = \frac{1}{2\pi * 5,7\text{kHz} * 6\text{k}} = 4,6\text{nF} \quad (35)$$

C9=4,7nF shall be chosen here.

#### 4.6 Self Biasing

##### PE4201/PE4301

Power supply of the PE4201/PE4301 during start up is provided through a high resistance resistor from the power grid input voltage. The maximum resistance has to be calculated resulting from the minimum input voltage and the required supply voltage of the PE4301 as well as the minimum required start up current.

$$R_{STUP} = \frac{\sqrt{2} * V_{in} - V_{ST}}{I_{ST}} = \frac{\sqrt{2} * 85\text{V} - 20\text{V}}{5\mu\text{A}} = 20\text{Meg}\Omega \quad (36)$$

To reduce start up time and account for leakage currents in the external diode the resistor is chosen to be 4MOhm. This is an experimental trade-off. Make sure the chosen resistor type has the proper power dissipation. Also, relatively high voltage over the resistor is to be accounted for (245V). It is recommended to use two 2MOhm resistors in series.

The capacitor on VDD has to provide power until the switching of the power-MOSFET has started and power will be provided from the help winding on the transformer. That can only happen after start-up and when the input voltage is at maximum level. At 50Hz this time  $t_{VDD}$  is about 10ms. Current consumption calculates from the IC supply current and the loss in the power-MOSFET when switching.

Power consumption of the IC is <450μA. Power-MOSFET switching consumption consists of an ohmic part (resistor on 'G') and the dynamical part in the MOSFET. This is a charge changing process at the gate capacitance in the device.

Switching frequency will not be constant over an input frequency period. It can be assumed to be 150 kHz on average. Also the duty cycle factor will not be constant. For simplicity it can be assumed to be 50%.

A simplified but sufficient equation to calculate the dynamic and ohmic portion is given in equation (37) and (38) respectively.

$$I_{Gdyn} = C_G * f * U_{Gmax} = 1nF * 150kHz * 8,5V = 1,275mA \quad (37)$$

$$I_{Gohm} = \frac{U_{Gmax}}{R_G} * T = \frac{8,5V}{20k\Omega} * 0,5 = 0,2125mA \quad (38)$$

Total current consumption calculates according to equation (39).

$$I_{VDD} = I_{stat} + I_{Gdyn} + I_{Gohm} = 0,45mA + 1,275mA + 0,2125mA = 1,9375mA \quad (39)$$

From that the capacitance of  $C_{VDD}$  can be calculated:

$$C_{VDD} = \frac{I_{VDD} * t_{VDD}}{V_{ST} - V_{LO}} = \frac{1,94mA * 10ms}{22V - 8V} = 1,38\mu F \quad (40)$$

The help winding on the transformer has to provide between 20 ... 25V DC.  
The Transformation Ration (TR) can be calculated according to equation (41):

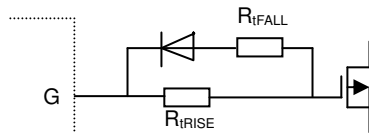
$$TR = \frac{V_{out}}{V_{VDD}} = \frac{405V}{22V} = 18,4 \quad (41)$$

#### 4.7 EMI and Driver SlewRate

##### PE4201/PE4301

The driver slew rate can be influenced a network according to figure 3.

Figure 3: Network for Driver Slew Rate



$R_{IFALL}$  determines the Slew Rate of the falling edge (in practice 4.7 to 6.8 $\Omega$ ). The diode should be a fast recovery Si-diode (MMSD914T1G).

$R_{IRISE}$  determines the Slew Rate of the rising edge (to optimize to gate capacity of the used FET, 18 to 56  $\Omega$ ). Caution has to be taken to meet EMI regulations.

#### 4.8 Start-Up Bypass Rectifier

##### PE4201/PE4301

A diode ( $D_{BYPASS}$ ) in parallel to the coil and the boost diode ( $D_{BOOST}$ ) reduces the current through the coil during start-up. It also pre-charges the bypass capacitor on the output to the peak input voltage.

This reduces over voltage peaks and currents in the coil and so improves EMI parameters. It also protects the power-MOSFET from over voltage damage. To reduce the current through the diode a series resistor shall be used.

In the range up to 80W, there is no need to use a bypass diode; the current depends on  $C_{out}$  in addition with possible start current on the load. In case of  $C_{out} = 47\mu F$  there is a max. current about 9A in a time window of 4ms. The rectifier, inductors and boost- diode ( $R_{sense}$  – PE4301) can handle it for such a short time.

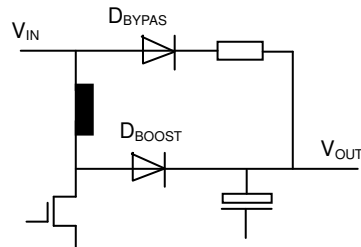


Figure 4: Bypass Rectifier

## 5 Description

The EVA4301-80 was designed to help understand and evaluate the features of the PE4201/PE4301 Power Factor Correction IC. Used external devices are standard components chosen for safe operation and do not represent a completely fine-tuned OEM application. The BOM (bill of material) for a final application may look slightly different.

The PE4201 is a wide input range controller IC for active power factor correction converters in CRMode with voltage mode PWM control.

The PE4301 is a wide input range controller IC for active power factor correction converters in CCMode with voltage mode frequency and PWM control.

**Please take caution since the board operates at 405V DC.**

#### 5.1 Evaluation Board Specifications

AC Line Input voltage .....	85 Vac - 265 VAC
AC Line Frequency .....	47 – 65 Hz
Switching Frequency in the middle .....	40 – 170 kHz
Output voltage .....	340- 405V DC
Output Load .....	max. 80W
Over Voltage Threshold .....	416V DC
Efficiency (@230V / 80W) .....	92%
Power Factor (@110V / 80W) .....	0.965
Power Factor (@230V / 80W) .....	0.990 (PE4301),
.....	0.988 (PE4201)
Operating Ambient Temp Range .....	0 – +40 °C

#### 5.2 Wire bridges

The board has been designed to provide evaluation support for the PE4301 as well as the PE4201 PFC ICs. For that reason the following wire bridges and components will have to be set properly.

	PE4201	PE4301
JP1	2_3	1_2
JP2	1_3	1_2
R2*, R11*, C12*	on Board	open
R7**, C11**, R23**	Open	on Board
R <sub>Sense</sub>	4x1.0Ω/0.1W	3x4.7Ω/0.5W

### 5.3 Schematic

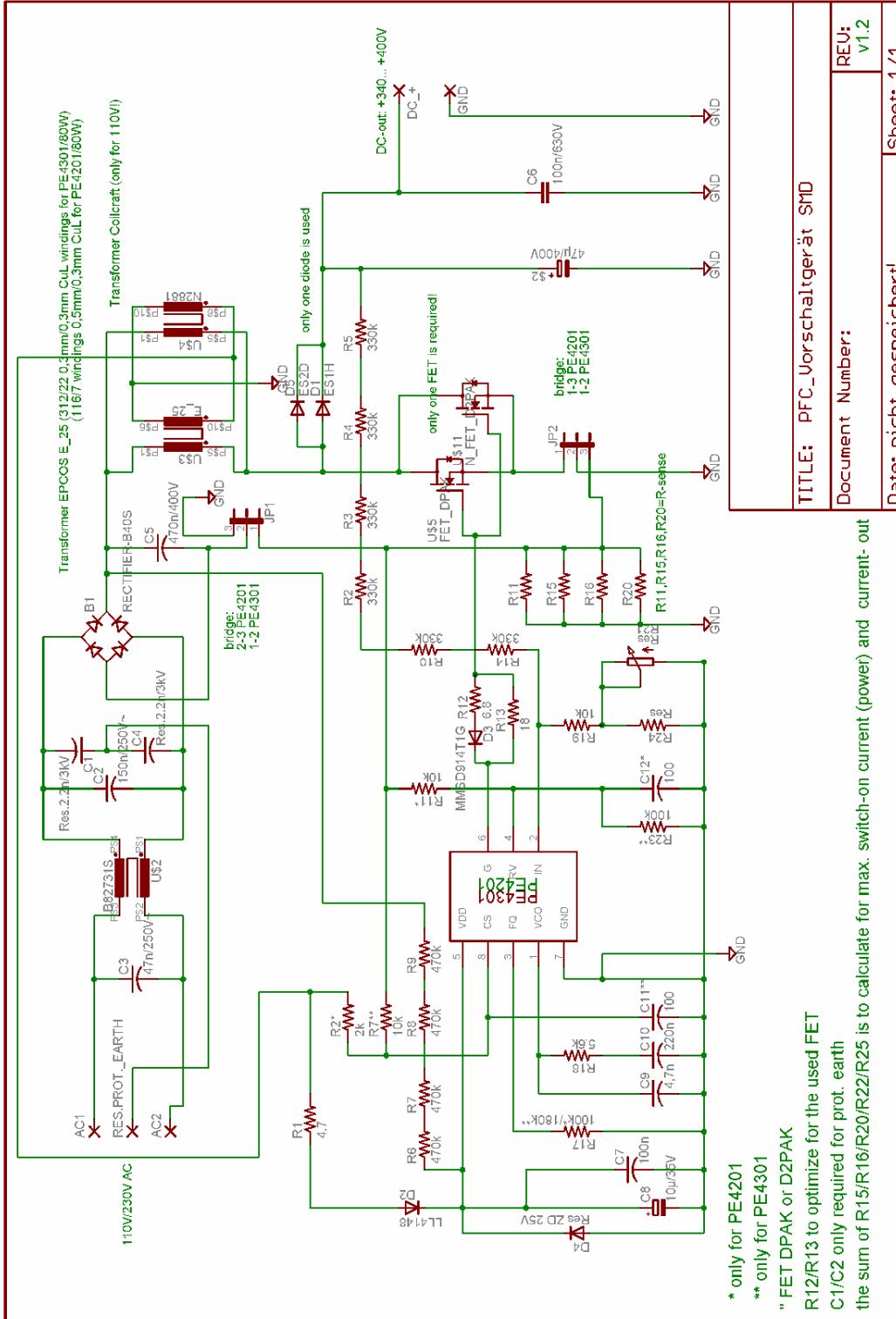


Figure 5: Board Schematic

#### 5.4 Component Placement

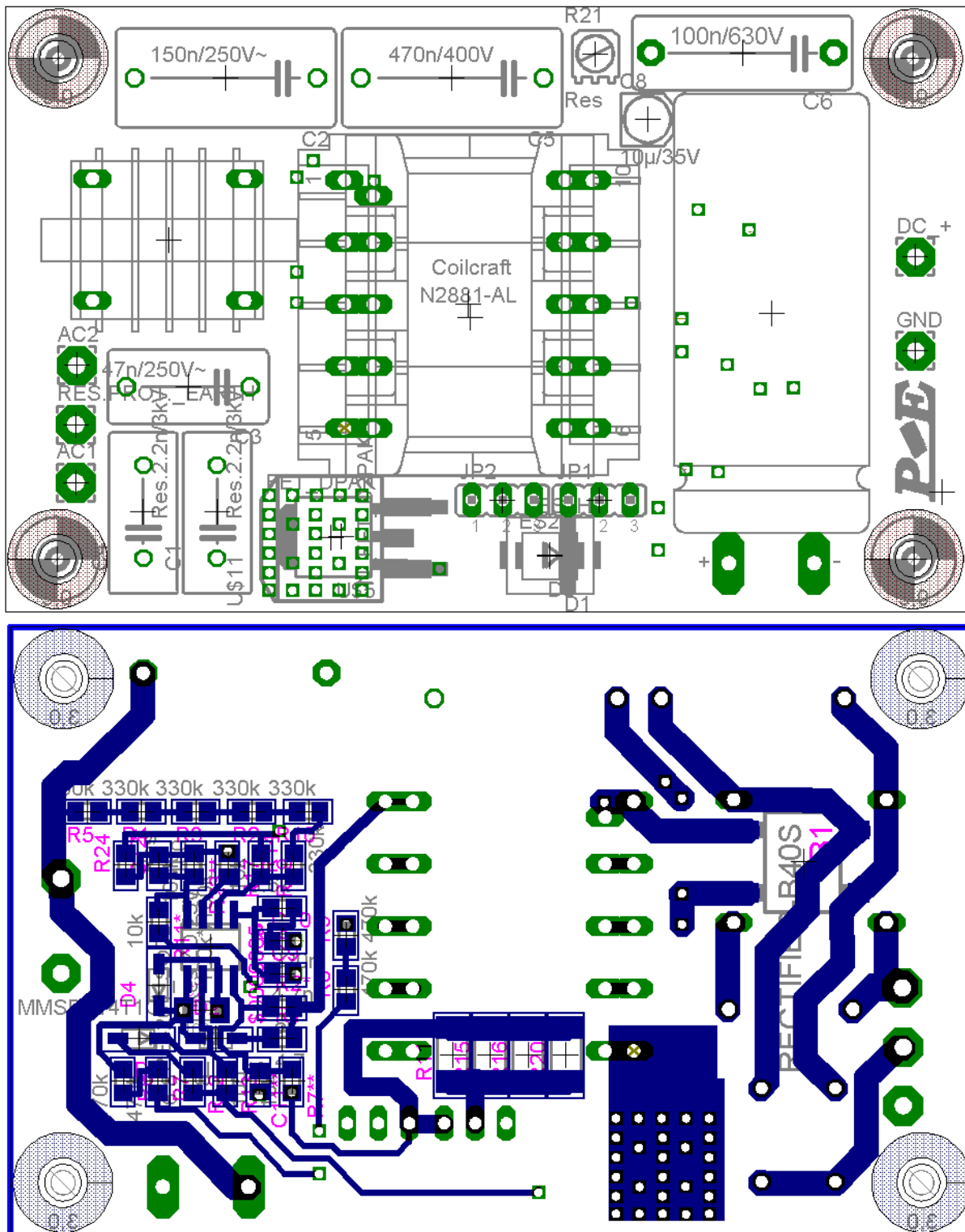


Figure 6: Board device population



#### 5.5 Board Picture and Layout

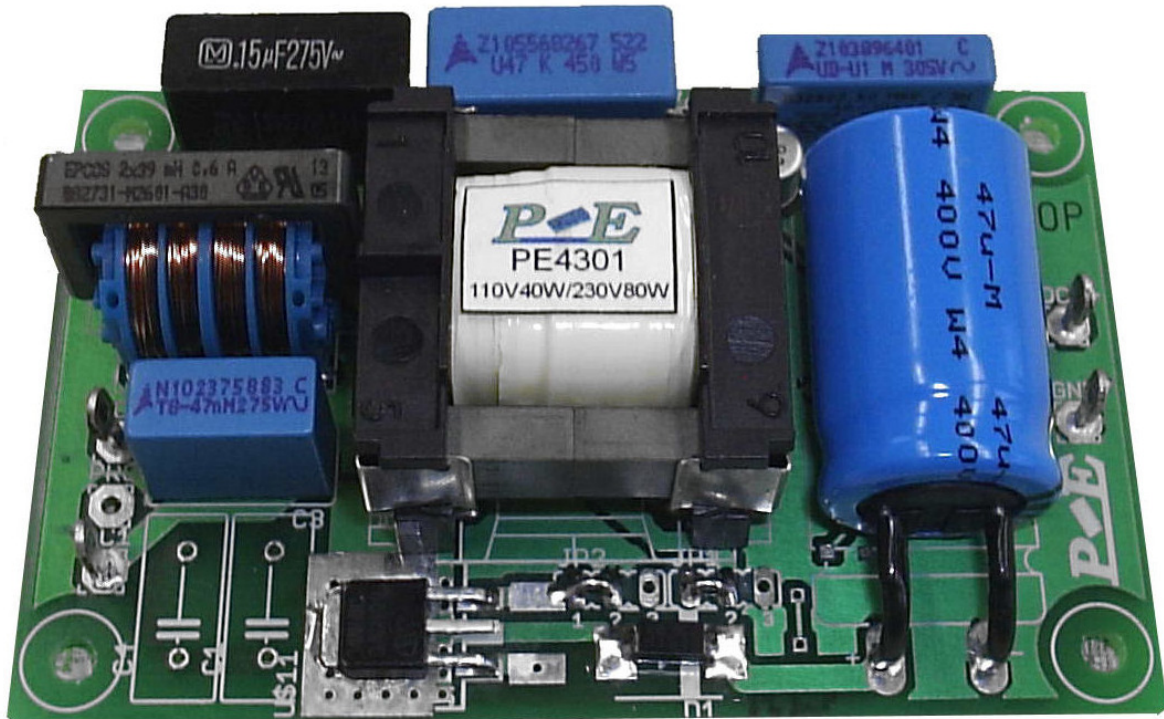


Figure 7: Board photograph (8cm x 5cm)

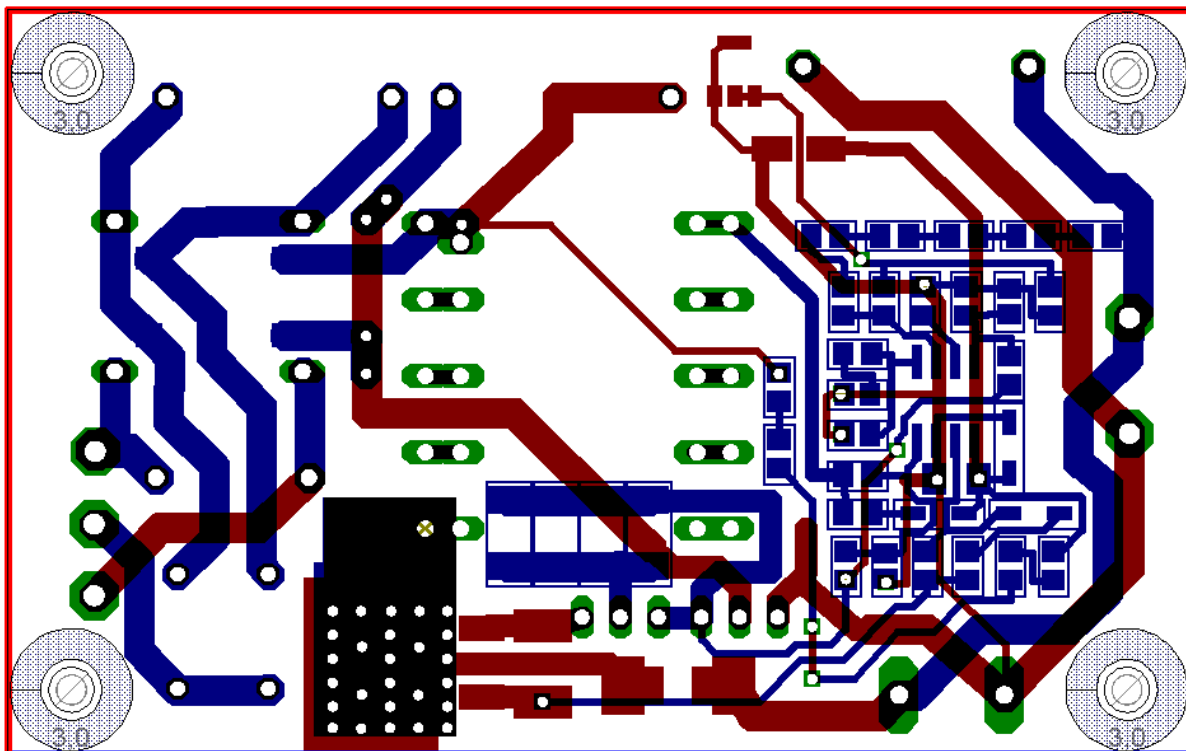


Figure 8: PCB Layout

#### 5.6 Bill of Material

Nr.	Reference	Used	Description/Package	Vendor
IC	1	PE4X01 SO08	PE4X01 SO08	PE4201 or PE4301
C1,C4	2	2.2n/3kV	C2N2	Res. f. Prot. Earth
C2	1	150n/250V~	C150-084X183	
C3	1	47n/250V~	C102-064X133	
C5	1	470n/400V	C150-084X183	
C6	1	100n/630V	C15B6	
C7	1	100n	C1206K	
C8	1	10µ/35V	153CLV-0405	
C9	1	4,7n	C0805	
C10	1	220n	C0805	
C11**	1	100p	C0805	not for PE4201
C12*	1	100p	C0805	not for PE4301
C13	1	47µ/400V	VRH	horizontal
D1	1	ES1H	SMC	
D2, D3	2	MMSD914T1G	SOD123	
D4	1	Res ZD 25V	SOD123	
R1	1	4.7 Ω	R0805	
R2, R3, R4, R5, R10, R14	6	330k	R0805	
R2*	1	2k	R0805	not for PE4301
R6, R7, R8, R9	4	470k	R0805	
R7**	1	10k	R0805	not for PE4201
R11, R19	2	10k	R0805	
R12	1	4.7- 6.8 Ω	R0805	optimize for FET
R13	1	18 - 56 Ω	R0805	optimize for FET
R11, R15, R16, R20,	4	1Ω/4.7 Ω	R0805/R2010(PE4301)	dep. on max. power
R17	1	100k/180k	R0805	PE4201/PE4301
R18	1	5.6k	R0805	
R21	1	Res (5k adjustable r.)	PC25	adjust DC-OUT
R23	1	100k	R0805	
R24	1	Res (tbd)	R0805	alternativ for R21 fixed
U\$1	1	B40S	B40S	rect. 1A/400V
U\$2	1	B82731S	B82731S	39mH filter EPCOS®™
U\$3	1	E 25 (EPCOS)	E25L	AL=91nH/n²
U\$4	1	N2881	N2881AL Coilcraft®™	only for 110V
U\$5	1	SPD07N60S5	DPAK	
U\$11	1	IRF840	D2PAK	
\$2	1	47µ/400V	VRH	horizontal
\$0000	1	PE4X01 SO08	PE4X01 SO08	PE4201 or PE4301
C1,C4	2	2.2n/3kV	C2N2	Res. f. Prot. Earth
C2	1	150n/250V~	C150-084X183	
C3	1	47n/250V~	C102-064X133	

## 6 Operating

### 6.1 Caution

The Evaluation board has been designed to operate between 40VAC and 80VAC input power grid voltages and 405VDC output voltage.

Powering the board outside specified operating conditions will destroy devices and might cause severe damage and harm people.

The board has been designed for a maximum load of 80VA. Overloading the output will cause overheating and destruction of devices.

Devices can heat up to 50°C in normal operation mode. Take caution to not burn your fingers.

Security measures for high voltage operation have to be taken.

### 6.2 Load

Resistive and electronic continuous loads up to 80VA at 450VDC can be applied on the output. The load can be applied on the DC-OUT terminal. Pay attention to the polarity and wire diameter.

### 6.3 AC-Input

The Input voltage has to be applied on the AC-IN terminal. An isolation transformer is required, especially when other power grid supplied measurement devices (oscilloscope, voltmeter) are being used to prevent from electrical shock or device damage. Avoid personal contact with the board when powered. Be aware that capacitors hold charges even when power will be turned off. Discharge the output capacitor through the load or a high ohmic load resistor after power off.

### 6.4 Power-up Sequence

Before input voltage will be turned on, all measurement devices should be connected. It is recommended to slowly turn up the input voltage with a regulation transformer, usually in combination with a separation transformer. Be aware that capacitors hold charges even when power will be turned off. Make sure they will be discharged before disconnecting the measurement devices.

The board has no explicit measuring points. You can measure on the IC.

Pin of IC

7	GND:	Ground, reference potential for all measuring points
5	VDD:	supply voltage for PE4201/4301, 0..30VZC
8	AC (PE4201):	help winding voltage through 2kOhm, -50..25V
8	CS (PE4301):	negative voltage of current sensor (-0,9.. -1,2V)
3	RG (PE4201):	voltage on RG, 1,03V (internal reverence)
3	FQ (PE4301):	voltage on FQ, 1,03V (internal reverence)
1	VCO:	voltage on output of regulation amplifier, 0 ... 5,5V
4	SH (PE4201):	voltage over Shunt resistor, 0 ... 0,5V
4	RV (PE4301):	adjust slew rate of the duty cycle
2	IN:	voltage in loop back, $V_{OUT}/160$ , 2,50 ... 2,65V
6	G:	voltage at IC-Pin G, power-MOSFET Gate driver voltage, typical 0 ... 8,5V
	Vout:	DCout +

## 7. List of Abbreviations

Abbreviation	Explanation
AC-IN	Input Voltage
$AC_{Lin}$	Input Current
BOM	Bill of material
CCM	Continuous Conduction Mode
$C_{EMI}$	Capacitor for EMI
$C_G$	Capacity of the gate (MOSFET)
$C_{HF}$	Capacitor for reduction of HF- transmitting
$C_{out}$	Output Capacitor
$C_{out2}$	Output Capacitor
$C_{SP}$	Cap. For
$C_{VVD}$	Cap. On Pin VDD
$C_z$	Cap. On Current Sense
CRM	Critical Conduction Mode
$D_{BOOST}$	Boost- Diode
$D_{BYPASS}$	Bypass- Diode
DCM	Discontinuous Conduction Mode
DC-OUT	Output Voltage
EMI	Electromagnetic Interferences
ESR	Equivalent series resistance
G	Output to Gate (MOSFET)
IN	Feedback- Input for Output- Voltage
$I_{OCP}$	Max. Current for switching of MOSFET
$I_{VCOmax}$	Max. VCO- Voltage
$I_{VDD}$	IC- Current
$L_{(CCM)}$	Inductivity in CCM
$L_{(CRM)}$	Inductivity in CRM
$L_{EMI}$	Inductor to reduce EMI
PFC	Powerfactor- Correction
$P_{in}$	Input- Power
$P_{out}$	Output- Power
PWM	Pulse- Width- Modulation
$R_G$	Clamping Resistor
$R_{STUP}$	Start-Up Resistor
$R_{iFALL}$	Fall-Time of Voltage on Gate
$R_{iRISE}$	Rise- Time of Voltage on Gate
THD	Total Harmonic Distortion
TR	Transformation Ration
$t_{VDD}$	Time for Starting the IC
$U_{Gmax}$	Max. Voltage on Gate
VCO	Voltage Controlled Oscillator
$V_{CSPCP}$	Voltage of Peak- Current- Protection
VDD	Operating Voltage of the IC
$V_{in}$	Voltage on Pin "IN"
$V_{LO}$	Lock Out Voltage
$V_{out}$	Output Voltage
$V_{RREF}$	Internal Reference of the IC
$V_{SHPCP}$	Max. Voltage on Input Current Protection
$V_{ST}$	Start UP Voltage

#### 8. Notes

## 9. Contact Addresses

### Germany

#### Stuttgart

Productivity Engineering  
Process Integration GmbH  
Behringstrasse 7  
D-71083 Herrenberg  
Germany  
Phone.: +49 (0) 70322798 0  
Fax: +49 (0) 70322798 29  
Email: [info@pe-gmbh.com](mailto:info@pe-gmbh.com)  
Web: [www.pe-gmbh.com](http://www.pe-gmbh.com)

#### Dresden

Productivity Engineering GmbH  
Branch  
Sachsenallee 9  
D-01723 Kesselsdorf  
Germany  
Phone.: +49 (0) 35204777 00  
Fax: +49 (0) 35204777 000  
Email: [info@pe-gmb.com](mailto:info@pe-gmb.com)

### Important Notice

Productivity Engineering GmbH (PE) reserves the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to PE's terms and conditions of sale supplied at the time of order acknowledgment. PE warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with PE's standard warranty. Testing and other quality control techniques are used to the extent PE deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed. PE assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using PE components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards. PE does not warrant or represent that any license, either express or implied, is granted under any PE patent right, copyright, mask work right, or other PE intellectual property right relating to any combination, machine, or process in which PE products or services are used. Information published by PE regarding third-party products or services does not constitute a license from PE to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from PE under the patents or other intellectual property of PE. Resale of PE products or services with statements different from or beyond the parameters stated by PE for that product or service voids all express and any implied warranties for the associated PE product or service and is an unfair and deceptive business practice. PE is not responsible or liable for any such statements.  
© 2016 PE GmbH. All rights reserved.

All trademarks and registered trademarks are the property of their respective owners.

The project is funded in parts by the European fund for regional development (EFRE) and the state of Saxony.